

TRANSIENT control rod

| Step | value [pcm] | pcm/step |
|------|-------------|----------|
| 0 | 0.0 | 0.0 |
| 5 | 0.1 | 0.0 |
| 10 | 0.3 | 0.0 |
| 15 | 0.5 | 0.1 |
| 20 | 1.0 | 0.1 |
| 25 | 1.5 | 0.1 |
| 30 | 2.1 | 0.1 |
| 35 | 2.9 | 0.2 |
| 40 | 3.8 | 0.2 |
| 45 | 4.8 | 0.2 |
| 50 | 6.0 | 0.2 |
| 55 | 7.2 | 0.3 |
| 60 | 8.6 | 0.3 |
| 65 | 10.1 | 0.3 |
| 70 | 11.8 | 0.3 |
| 75 | 13.6 | 0.4 |
| 80 | 15.5 | 0.4 |
| 85 | 17.5 | 0.4 |
| 90 | 19.7 | 0.5 |
| 95 | 22.1 | 0.5 |
| 100 | 24.6 | 0.5 |
| 105 | 27.3 | 0.5 |
| 110 | 30.1 | 0.6 |
| 115 | 33.1 | 0.6 |
| 120 | 36.3 | 0.7 |
| 125 | 39.6 | 0.7 |
| 130 | 43.1 | 0.7 |
| 135 | 46.9 | 0.8 |
| 140 | 50.8 | 0.8 |
| 145 | 54.9 | 0.8 |
| 150 | 59.3 | 0.9 |
| 155 | 63.8 | 0.9 |
| 160 | 68.6 | 1.0 |
| 165 | 73.7 | 1.0 |
| 170 | 79.0 | 1.1 |
| 175 | 84.5 | 1.1 |
| 180 | 90.4 | 1.2 |
| 185 | 96.5 | 1.3 |
| 190 | 102.8 | 1.3 |
| 195 | 109.5 | 1.4 |
| 200 | 116.6 | 1.4 |
| 205 | 123.9 | 1.5 |
| 210 | 131.5 | 1.6 |
| 215 | 139.6 | 1.6 |
| 220 | 148.0 | 1.7 |
| 225 | 156.7 | 1.8 |
| 230 | 165.8 | 1.9 |
| 235 | 175.3 | 1.9 |
| 240 | 185.2 | 2.0 |
| 245 | 195.4 | 2.1 |
| 250 | 206.2 | 2.2 |
| 255 | 217.3 | 2.3 |
| 260 | 228.8 | 2.4 |
| 265 | 240.8 | 2.4 |
| 270 | 253.3 | 2.5 |
| 275 | 266.1 | 2.6 |
| 280 | 279.4 | 2.7 |
| 285 | 293.2 | 2.8 |
| 290 | 307.4 | 2.9 |
| 295 | 322.1 | 3.0 |

| Step | value [pcm] | pcm/step |
|------|-------------|----------|
| 300 | 337.3 | 3.1 |
| 305 | 353.0 | 3.2 |
| 310 | 369.0 | 3.3 |
| 315 | 385.5 | 3.4 |
| 320 | 402.6 | 3.5 |
| 325 | 420.1 | 3.5 |
| 330 | 438.1 | 3.6 |
| 335 | 456.5 | 3.7 |
| 340 | 475.4 | 3.8 |
| 345 | 494.7 | 3.9 |
| 350 | 514.3 | 4.0 |
| 355 | 534.6 | 4.1 |
| 360 | 555.2 | 4.2 |
| 365 | 576.2 | 4.2 |
| 370 | 597.7 | 4.3 |
| 375 | 619.6 | 4.4 |
| 380 | 641.8 | 4.5 |
| 385 | 664.3 | 4.6 |
| 390 | 687.4 | 4.6 |
| 395 | 710.7 | 4.7 |
| 400 | 734.3 | 4.8 |
| 405 | 758.4 | 4.8 |
| 410 | 782.7 | 4.9 |
| 415 | 807.3 | 5.0 |
| 420 | 832.2 | 5.0 |
| 425 | 857.4 | 5.1 |
| 430 | 882.9 | 5.1 |
| 435 | 908.5 | 5.2 |
| 440 | 934.5 | 5.2 |
| 445 | 960.7 | 5.3 |
| 450 | 987.0 | 5.3 |
| 455 | 1013.6 | 5.3 |
| 460 | 1040.3 | 5.4 |
| 465 | 1067.3 | 5.4 |
| 470 | 1094.3 | 5.4 |
| 475 | 1121.5 | 5.5 |
| 480 | 1148.9 | 5.5 |
| 485 | 1176.4 | 5.5 |
| 490 | 1203.9 | 5.5 |
| 495 | 1231.6 | 5.5 |
| 500 | 1259.4 | 5.6 |
| 505 | 1287.2 | 5.6 |
| 510 | 1315.1 | 5.6 |
| 515 | 1343.1 | 5.6 |
| 520 | 1371.1 | 5.6 |
| 525 | 1399.1 | 5.6 |
| 530 | 1427.2 | 5.6 |
| 535 | 1455.3 | 5.6 |
| 540 | 1483.4 | 5.6 |
| 545 | 1511.5 | 5.6 |
| 550 | 1539.6 | 5.6 |
| 555 | 1567.8 | 5.6 |
| 560 | 1595.9 | 5.6 |
| 565 | 1623.9 | 5.6 |
| 570 | 1652.0 | 5.6 |
| 575 | 1680.0 | 5.6 |
| 580 | 1708.0 | 5.6 |
| 585 | 1735.9 | 5.6 |
| 590 | 1763.7 | 5.6 |
| 595 | 1791.5 | 5.6 |

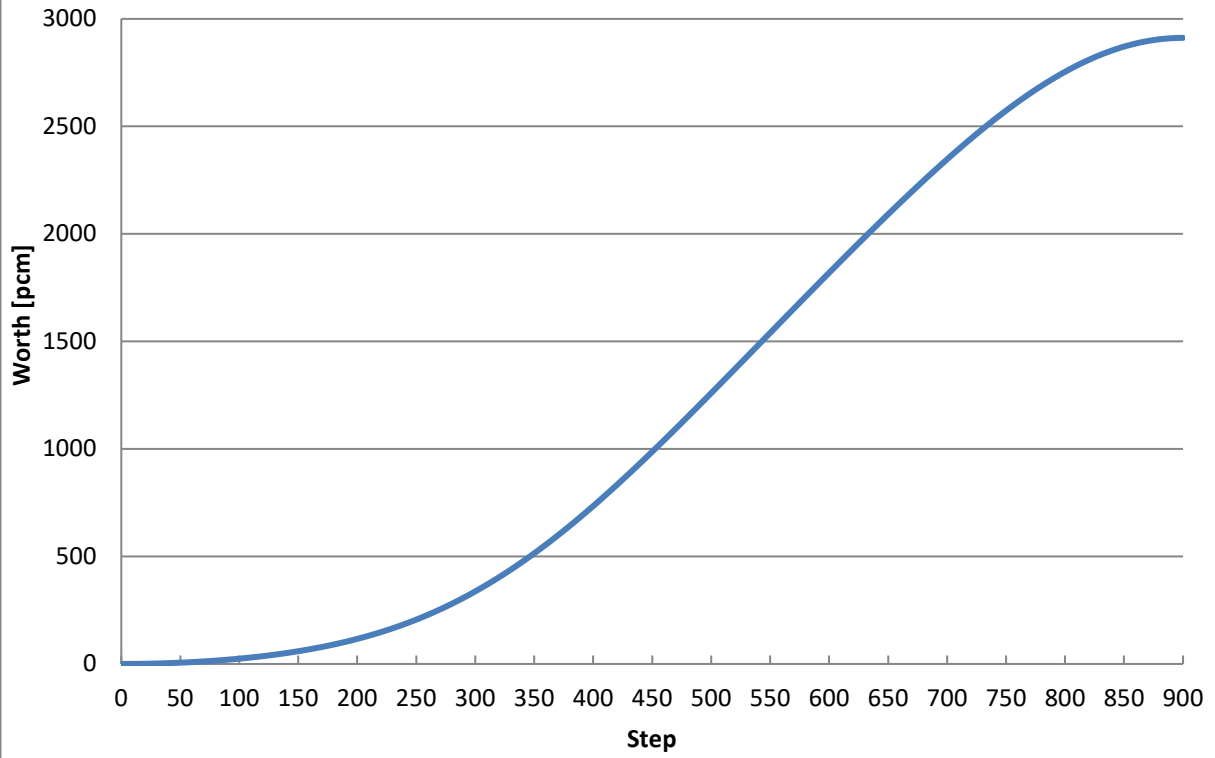
| Step | value [pcm] | pcm/step |
|------|-------------|----------|
| 600 | 1819.3 | 5.5 |
| 605 | 1846.9 | 5.5 |
| 610 | 1874.5 | 5.5 |
| 615 | 1902.0 | 5.5 |
| 620 | 1929.4 | 5.5 |
| 625 | 1956.7 | 5.4 |
| 630 | 1983.9 | 5.4 |
| 635 | 2010.9 | 5.4 |
| 640 | 2037.9 | 5.4 |
| 645 | 2064.7 | 5.3 |
| 650 | 2091.3 | 5.3 |
| 655 | 2117.8 | 5.3 |
| 660 | 2144.1 | 5.2 |
| 665 | 2170.2 | 5.2 |
| 670 | 2196.2 | 5.2 |
| 675 | 2221.9 | 5.1 |
| 680 | 2247.4 | 5.1 |
| 685 | 2272.7 | 5.0 |
| 690 | 2297.7 | 5.0 |
| 695 | 2322.5 | 4.9 |
| 700 | 2347.0 | 4.9 |
| 705 | 2371.3 | 4.8 |
| 710 | 2395.1 | 4.8 |
| 715 | 2418.7 | 4.7 |
| 720 | 2442.1 | 4.6 |
| 725 | 2464.9 | 4.5 |
| 730 | 2487.4 | 4.5 |
| 735 | 2509.6 | 4.4 |
| 740 | 2531.4 | 4.3 |
| 745 | 2552.6 | 4.2 |
| 750 | 2573.5 | 4.1 |
| 755 | 2594.0 | 4.0 |
| 760 | 2613.9 | 3.9 |
| 765 | 2633.3 | 3.8 |
| 770 | 2652.2 | 3.7 |
| 775 | 2670.7 | 3.6 |
| 780 | 2688.5 | 3.5 |
| 785 | 2705.7 | 3.4 |
| 790 | 2722.5 | 3.3 |
| 795 | 2738.5 | 3.2 |
| 800 | 2754.0 | 3.0 |
| 805 | 2768.8 | 2.9 |
| 810 | 2783.1 | 2.8 |
| 815 | 2796.5 | 2.6 |
| 820 | 2809.2 | 2.5 |
| 825 | 2821.4 | 2.4 |
| 830 | 2832.9 | 2.2 |
| 835 | 2843.5 | 2.1 |
| 840 | 2853.4 | 1.9 |
| 845 | 2862.7 | 1.8 |
| 850 | 2871.1 | 1.6 |
| 855 | 2878.7 | 1.5 |
| 860 | 2885.6 | 1.3 |
| 865 | 2891.8 | 1.1 |
| 870 | 2897.0 | 1.0 |
| 875 | 2901.5 | 0.8 |
| 880 | 2905.3 | 0.7 |
| 885 | 2908.1 | 0.5 |
| 890 | 2910.1 | 0.3 |
| 895 | 2911.3 | 0.2 |
| 900 | 2911.9 | 0.0 |

Operator: Sebastjan Rupnik

Measured by: Andraž Verdir

Total worth in \$:
4.16 \$

TRANSIENT ROD - INTEGRAL WORTH



TRANSIENT ROD - DIFFERENTIAL WORTH

